



ELIZADE UNIVERSITY, ILARA-MOKIN, ONDO STATE
FACULTY OF ENGINEERING
DEPARTMENT OF ELECTRICAL AND COMPUTER ENGINEERING

SEMESTER II EXAMINATION, 2016/2017 ACADEMIC SESSION

COURSE TITLE: CONTROL THEORY

COURSE CODE: EEE 318

EXAMINATION DATE: 2nd AUGUST 2017

COURSE LECTURER: DR. OGIDAN O.K.

A rectangular box containing a handwritten signature in black ink.

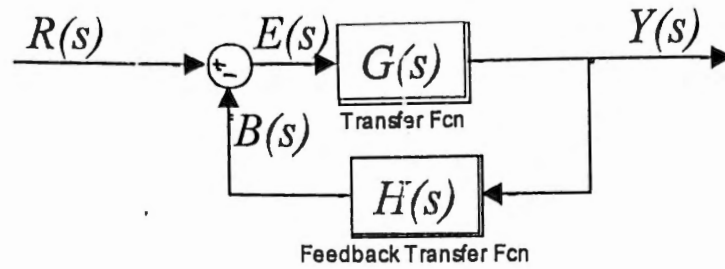
HOD's SIGNATURE

TIME ALLOWED: 3HRS.

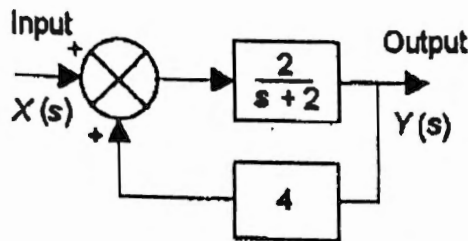
INSTRUCTIONS:

1. ANSWER ANY 5 OUT OF THE 7 QUESTIONS
2. SEVERE PENALTIES APPLY FOR MISCONDUCT, CHEATING, POSSESSION OF UNAUTHORIZED MATERIALS DURING EXAM.
3. YOU WILL BE PROVIDED WITH A TIME/LAPLACE TRANSFORM SHEET FOR THIS EXAM.
4. YOU ARE **NOT** ALLOWED TO BORROW CALCULATORS AND ANY OTHER WRITING MATERIALS DURING THE EXAMINATION.

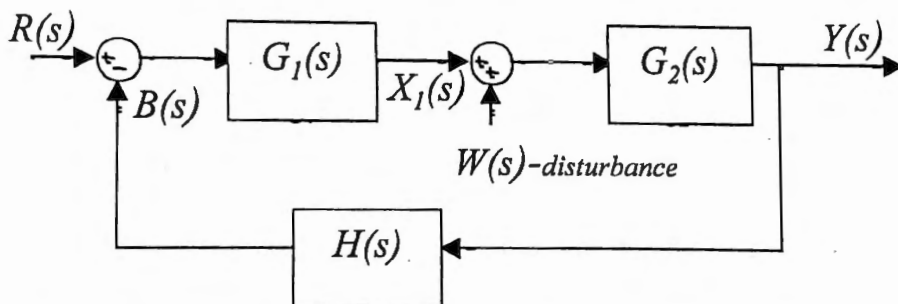
Question 1



- a) Given the block diagram in the diagram above, find the closed loop transfer function. (3 marks)
- b) Determine the overall transfer function of a system with a forward path transfer function of $\frac{2}{(s+2)}$ and a feedback transfer function of 4. (3 marks)



- c.) Consider a system under disturbance as shown below. Determine the overall closed loop transfer function of such a system:



- i.) Without disturbance, ii.) with disturbance iii.) with and without disturbance. (6 marks)

Question 2

- a.) What are the differences between open loop and closed loop system?
- b.) Outline the differences between on-off control and the Proportional Integral Derivative (PID) control (6 marks)
- c.) Write the following differential equations in the Laplace (s) domain

i. $F = m \frac{d^2 y}{dt^2} + c \frac{dy}{dt} + ky$, initial value of variable $y = 0$ at $t = 0$

ii. $v = RC \frac{dv_c}{dt} + v_c$, initial value of variable $v = 0$ at $t = 0$

iii. $\frac{d^2y}{dt^2} + 2\zeta\omega_n \frac{dy}{dt} + \omega_n^2 y = k\omega_n^2 x$, initial value of variable $y=0$ at $t=0$

(6 marks)

Question 3

a.) A control system has two elements in series with transfer functions of $\frac{1}{(S+2)}$ and $\frac{1}{(S+4)}$

i.) Determine the overall transfer function

ii.) Write a programme (to be run in the MATLAB workspace) that inputs a unit step function into the system and to output a steady state response. (5 marks)

b.) A system has an output y related to the input x by the differential equation: $\frac{d^2y}{dt^2} + 5\frac{dy}{dt} + 6y = x$

What will be the output from the system when it is subjected to a unit step input? Initially both the input and output are zero.

Hint: Use the Time/Laplace domain transformation table.

(7 marks)

Question 4

a.) What are the differences between differential equation and transfer function? (2 marks)

b.) Outline the differences between first order and second order systems. (2 marks)

c.) Give two examples of a second order system. (2 marks)

d.) Give two examples of a first order system. (2 marks)

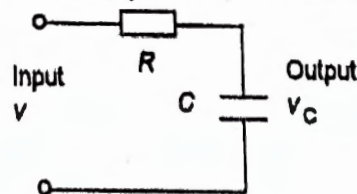
e.) A system has a transfer function $\frac{1}{(s+5)}$. What will be its output as a function of time when it is subjected to a unit step input of 1V? (4 marks)

Question 5

a.) Describe the concept of stability and its importance in control system. (2 marks)

b.) Compare and contrast between classical and modern control systems. (4 marks)

c.) Consider a circuit with a resistor R and capacitor C in series:



i.) Determine the transfer function for the circuit in c.

ii.) What will be its output as a function of time if it is subjected to a 5V ramp input? (6 marks)

Question 6

a.) Define briefly the following

- I. Transfer function
- II. Modeling
- III. System identification
- IV. Bode plot
- V. Nyquist stability criterion

(5 marks)

b.) A system has a transfer function: $G(s) = \frac{2}{(s+5)}$. Determine the magnitude and phase of the output from the system when it is subjected to a sinusoidal input of $2\sin 3t$. (7 marks)

Question 7

a.) When is a system be said to be stable?

(2 marks)

b.) Given the following transfer functions, state which of them are stable or unstable and plot their positions in the s-plane.

i.) $G(s) = \frac{1}{s^2 + 3s + 2}$

ii.) $G(s) = \frac{1}{s^2 - 3s + 2}$

iii.) $G(s) = \frac{1}{s^2 + 2s + 4}$

iv.) $G(s) = \frac{1}{s^2 - 2s + 4}$

v.) $G(s) = \frac{1}{(s+1)^2}$

(5 marks)

c.) Give n a second order system: $G(s) = \frac{1}{s^2 + 3s + 2}$ which is subjected to a unit step input.

- i.) Express as a function of time and
- ii.) State if it is a stable system or not in relation to its transient (exponential) terms and give reasons for your answer

(5 marks)

Time function / Laplace transform table

Time function $f(t)$	Laplace transform $F(s)$
1 A unit impulse	1
2 A unit step	$\frac{1}{s}$
3 t , a unit ramp	$\frac{1}{s^2}$
4 e^{-at} , exponential decay	$\frac{1}{s+a}$
5 $1 - e^{-at}$, exponential growth	$\frac{a}{s(s+a)}$
6 $t e^{-at}$	$\frac{1}{(s+a)^2}$
7 $1 - \frac{1 - e^{-at}}{a}$	$\frac{1}{s^2(s+a)}$
8 $e^{-at} - e^{-bt}$	$\frac{b-a}{(s+a)(s+b)}$
9 $(1-a)e^{-at}$	$\frac{1}{(s+a)^2}$
10 $1 - \frac{b}{b-a} e^{-at} + \frac{a}{b-a} e^{-bt}$	$\frac{ab}{a(s-a)(s+b)}$
11 $\frac{e^{-at}}{(b-a)(c-a)} + \frac{e^{-bt}}{(c-a)(a-b)} + \frac{e^{-ct}}{(a-c)(b-c)}$	$\frac{1}{(s-a)(s+b)(s+c)}$
12 $\sin \omega t$, a sine wave	$\frac{\omega}{s^2 + \omega^2}$
13 $\cos \omega t$, a cosine wave	$\frac{s}{s^2 + \omega^2}$
14 $e^{-at} \sin \omega t$, a damped sine wave	$\frac{\omega}{(s-a)^2 + \omega^2}$
15 $e^{-at} \cos \omega t$, a damped cosine wave	$\frac{s-a}{(s-a)^2 + \omega^2}$
16 $\frac{\omega}{\sqrt{1-\zeta^2}} e^{-\zeta t} \sin(\omega \sqrt{1-\zeta^2} t)$	$\frac{\omega^2}{s^2 + 2\zeta\omega s + \omega^2}$
17 $1 - \frac{1}{\sqrt{1-\zeta^2}} e^{-\zeta t} \sin(\omega \sqrt{1-\zeta^2} t + \phi)$, $\cos \phi = \zeta$	$\frac{\omega^2}{s^2 + 2\zeta\omega s + \omega^2}$